

ABSTRACT OF THE DISCLOSURE

A force-feedback input device includes an operation section to be operated by an operator; a position detection section for detecting the operating state of the operation section; a force-feedback generation section for applying force feedback to the operation section; an external device, and a haptic commander for controlling the driving of the force-feedback generation section on the basis of position information output from the position detection section and part data transmitted from the external device, and applying predetermined force feedback to the operation section according to the operating state thereof. The haptic commander includes a part data storage section for storing the part data transmitted from the external device, and a part data management table for managing the enabled and disabled states of each piece of the part data stored in the part data storage section.